

# International Journal of Innovative Research in Computer and Communication Engineering

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# Review on "Computer-Aided Image Processing Techniques for Lung Tumor Detection Using CT scan Images."

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**ABSTRACT:** Lung cancer is one of the growing problems in world and moreover lung cancer detection in the early stage has become a problem. To save the lives of people early diagnosis should be done. Lung cancer detection can be done with CT scan imaging but it is difficult for doctors to identifies the cancer cells from CT scan images. So with the increase in demand of computers some computer aided techniques in the medical science, image processing and machine learning has been implemented. The methods help doctor to detect cancer accurately on Time. The aim is to study the different computer-aided techniques, and compare it with current best technique to find out limitation and finally propose the new model. The lung cancer detection technique are sorted and listed on the basis of their detection accuracy. The methods are analyzed and compared to find changes in accuracy. Therefore, target is to increase the accuracy towards 100%. The comparison of different system is done to find out best method for Lung cancer detection

**KEYWORDS:** CT scan image, Lung nodule, computed tomography, computer-aided detection, support vector machine (SVM)

#### I. INTRODUCTION

Cancer is diseases that people are particularly worried and afraid now a day. in 2016, 8.9 million people are estimated to have died from the various forms of cancer. Every sixth death in the world is due to cancer and lung cancer is one of the most deadly diseases. The main cause is the formation of cancerous nodules around the lobe or lung. Therefore, early detection of nodules is very importantnowadays lung cancer has rising due to the change in environment and lifestyle. Lung cancer can become the causes of deaths. In some cases early symptoms can detect cancer in early stage but it become difficult to detect cancer in final stage as symptoms are observed late. Cancer spreads very rapidly in our body. However in some cases diagnosis fails to detect cancer in early stages due to poor detection techniques. best practice used in medical science is the CT scanning technique as it can identify every suspected and unsuspected lung cancer nodules [3]. But due to the change in the intensity of CT scan images and anatomical structure misjudgment by doctors and radiologists it becomes difficult to find the cancer cell [4]. Recently, computer aided diagnosis has helped doctors to reduce the rate of failure in cancer detection [5]. Many systems are proposed to detect cancer and more research is undergone, it is found that, some systems don't give 100 percent accuracy. Image processing techniques and machine learning techniques has been implemented to detect and classify the lung cancer and analysis is done to propose a best system for cancer detection.

# II. LITERATURE REVIEW

A survey shows different methods for lung cancer detection.

1. Aggarwal, Furquan and Kalra [4] proposed a model that provides classification between nodules and normal lung anatomy structure. The method extracts geometrical, statistical and gray level characteristics. LDA is used as classifier and optimal thresholding for segmentation. The system has 84 percent accuracy and still fails to detect cancer completely. No any machine learning techniques has been used to classify and simple segmentation techniques is used. Therefore, combination of any of its steps in our new model does not provide probability of



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#### improvement.

- 2. Jin, Zhang and Jin [5] used convolution neural network as classifier in his CAD system to detect the lung cancer. The system has 84.6% of accuracy, 82.5% of sensitivity and 86.7% of specificity. It uses circular filter in Region of interest (ROI) extraction phase which reduces the cost of training and recognition steps. Still it gives unsatisfactory results.
- 3) Sangamithraa and Govindaraju [6] uses K mean unsupervised learning algorithm for clustering or segmentation. It groups the pixel dataset according to certain characteristics. Features like entropy, correlation, homogeneity, PSNR, SSIM are extracted using gray-level co-occurrence matrix (GLCM) method. The system has accuracy of about 90.7%. Median filter is used for noise removal and to increase accuracy
- 4) Roy, Sirohi, and Patle [7] developed system to detect lung cancer nodule using fuzzy interference system and active contour model. This system uses gray transformation for image contrast enhancement. Image binarization is performed before segmentation and resulted image is segmented using active contour model. Cancer classification is performed using fuzzy inference method. Features like area, mean, entropy, correlation, major axis length, minor axis length are extracted to train the classifier. Overall, accuracy of the system is 94.12%. Counting its limitation it does not classify the cancer as benign or malignant which is future scope of this proposedmodel.
- 5) Ignatious and Joseph [8] developed a system using watershed segmentation. In preprocessing it uses Gabor filter to enhance the image quality. It compares accuracy with neural fuzzy model and region growing method. Accuracy of the proposed is 90.1% which is higher than model with segmentation using neural fuzzy model and region growing method. The model solves the over segmentation problem using marker controlled watershedas a limitation it does not classify the cancer as benign or malignant and accuracy is high but still not satisfactory. Some change has increases the accuracy.

The Analyzing the literature reviews, on the basis of accuracy and advantages of the steps used, the system proposed by Ignatious and Joseph [8] is good.

#### III. DIFFERENT METHODOLOGY

#### 3.1 Lung cancer detection using Gabor filter.

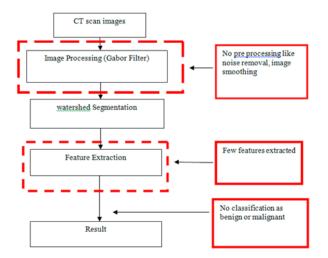


Fig 3.1: Current Method proposed by Ignatious and Joseph [8]

# 3.1.1 Method uses,

- Gabor filters to enhance the image
- Marker controlled watershed method for segmentation and detects the cancer nodule.
- This model extracts the features like area, perimeter, and eccentricity only of the cancer nodules.



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#### 3.1.2 The system has some limitation

- Only few features has been extracted for cancernodules
- No preprocessing like noise removal, image smoothing available

To overcome the limitation of current system a new method is proposed

### 3.2 Lung cancer detection using Median and Gaussian filter

### 3.2.1 Additional features in proposed system

- Use of Median filter and Gaussian filter Instead of Gabor Filter has been implemented in pre-processing stage.
- In addition to features like area, perimeter and eccentricity, features like Centroid, Diameter and pixel Mean Intensity have been extracted in feature extraction stage for the detected cancer nodules.
- The feature extraction and calculation of accuracy is also done.
- But, its classification as benign or malignant has not been implemented. An additional stage of classification of cancer nodule is performed using Support Vector Machine.

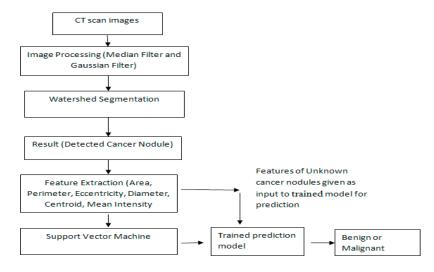


Fig 3.2: proposed model using Median and Gaussian filter

### 3.2.2 Function of each block in proposed system

#### Image Preprocessing

Median filter is used on gray scale image of CT scan images. Noise gets added at the time of image acquisition and that noise can be detected as cancer. Median filter helps to remove these noises. Median filter removes salt and pepper noise from the CT images [11]. Gaussian filter smoothes the image and remove speckle noise.

#### Segmentation

Segmentation helps to get area of interest by location object or boundaries. This process locates objects or boundaries which help in acquiring the region of interest in the image. It divides the image into parts. In lung cancer detection it segments the cancer nodule from the CT scan image. Watershed segmentation is implemented. Its main feature is that it can separate and identify the touching objects in the image. This feature helps in proper segmentation of cancer nodules if it is touching to other false nodules.

#### Features extraction

In this stage, features like area, perimeter, centroid, diameter, and eccentricity and Mean intensity. These features later on are used as training features to developclassifier.

Classification

It classifies the detected nodule as malignant or benign. Support vector machine (SVM). SVM defines the function



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that classifies data into two classes [9]. The function is defined as  $D(x) = w^T x_i + b$  where  $x_i$  is training inputs,  $w^T$  is m dimensional vector, and b is bias term. Here, i=1...M.

 $\begin{aligned} &D(x) = &w^Tx_i + b \geq 1 \text{ for } y_i = 1 \\ &D(x) = &w^Tx_i + b \leq -1 \text{ for } y_i = -1 \end{aligned}$ 

### 3.2.3 Advantages and Limitations

Advantages of proposed model.

- Increase in accuracy
  - Classifies the detected lung cancer as malignant orbenign.
  - Removes salt-pepper noises and speckle noise that creates false detection of

#### cancer

Limitation of proposed model.

- Accuracy has increased but not reached 100 percent
- It classifies cancer as just malignant or benign but does not classify into different stages like stage I, II, III, and IV.

### 3.3 Lung detection using image processing techniques in computed tomography

This method includes all type of nodule detection thus increasing the accuracy of system. This is done by an image processing method for detecting ground glass opacity(GGO), partsolid, and solid nodules in chest computed tomography.

## 3.3.1 The method includes

- Imagepreprocessing.
- Lung segmentation.
- Noduleenhancement.
- Candidate detection.
- · Reduction of false positive.



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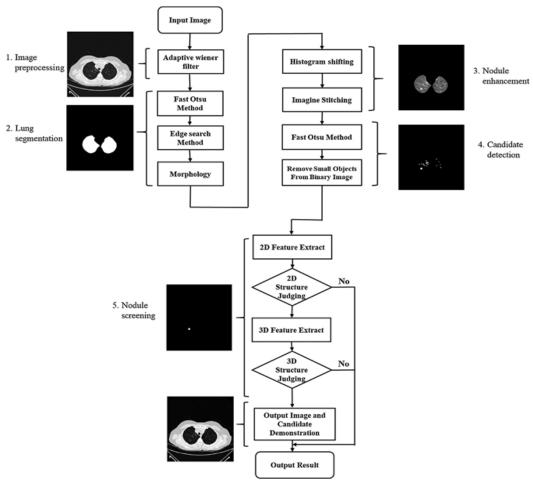


Fig 3.3 flow chart of proposed system

# 3.3.2 Function of each block in proposed system

- Preprocessing -The preprocessing uses an adaptive Wiener filter to optimize the images.
- Lung segmentation-The lung segmentation uses Fast Otsu method and the edge search method for rapidsegmentationanduseshistogramshiftingtocreateimageswiththesame reference. The edge search is replaced by computing-intensive iterative hole-filling method. The advantage is to extract extensively distributed grey levels.
- Nodule enhancement—The image accumulation and cumulative method is used to enhance grey level of nodules
- Candidate detection-Uses fast Otsumethod to get preliminary objects and reduces false positives
  the system uses quadratic SVM to obtain the nodules To remove false positive SVM is used twice,
  in first run nodules are obtained and results are detected in second run

#### 3.3.3Advantages

• The innovative edge search method saves 3 times computing time and accelerates the acquisition of lung shielding.



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• A new 3D feature is proposed for lung nodule detection

#### IV. DISCUSSION AND CONCLUSION

- 1. Lung cancer detection using Gabor filter has no satisfactory result of accuracy with 82 %. The system does not classify degree of cancer nodules.
- 2. Therefore the modified method of Lung cancer detection using Median and Gaussian filter uses SVM for detection of nodule as malignant and benign with 92 percent accuracy which is higher than previous method. But the new system does not classify cancer in stages of I, II, III, and IV. So in future a system can be implemented to classify cancer in different stages.
- 3. The third method Lung detection using image processing techniques in computed tomography uses an innovative edge detection which save 3 times the computing time. Based on the characteristics of repeated nodules system can effectively and quickly find GGOs with low brightness. The fast Otsu method helped to obtain binarized threshold quickly
- 4. To reduce number of object after binarization a two dimensional classification is implemented, which saved time and accelerated the acquisition of real nodule
- 5. The total system sensitivity is increased to 92.05% and system accuracy o find out smaller nodules also to 93.73%

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