



# International Journal of Innovative Research in Computer and Communication Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 5, May 2016

## A Novel Image Super-Resolution

K. Rajesh Kumar<sup>1</sup>, A.N. Sai Chakravarthy<sup>2</sup>

Assistant Professor, Dept of ECE, Keshav Memorial Institute of Technology, Hyderabad, Telangana, India<sup>1</sup>

Assistant Professor, Dept of ECE, Keshav Memorial Institute of Technology, Hyderabad, Telangana, India<sup>2</sup>

**ABSTRACT:** Super-resolution (SR) image reconstruction is the process of combining several low resolution images into a single higher resolution image or Generating high resolution image from a single low resolution image. There is a driving need for digital images of higher resolutions and quality. In order to improve the resolution and perceptual quality of such web image/video, we bring forward a sensible solution which mixes adaptive regularization and learning-based super-resolution. The contribution of this work is twofold. First, we tend to propose to research the image energy modification characteristics during the iterative regularization process, i.e., the energy change magnitude relation between primitive (e.g., edges, ridges and corners) and non-primitive fields supported there revealed convergence property of the energy modification magnitude relation, acceptable regularization strength will then be determined to well balance compression artifacts removal and primitive elements preservation. Second, we tend to verify that this adaptive regularization can steady and greatly improve the try matching accuracy in learning-based super-resolution.

**KEYWORDS:** Adaptive regularization, compression artifacts removal, energy change ratio, learning-based super-resolution (SR).

### I. INTRODUCTION

High-resolution images or videos are required in most digital imaging applications. Higher resolution offers an improvement of the graphic information for human perception. It is also useful for the later image processing, computer vision etc. Image resolution is closely related to the details included in any image. In general, the higher the resolution is, the more image details are presented. Super-resolution, loosely speaking, is the process of recovering a high-resolution image from a set or single low resolution input image. Any given set of source low resolution (LR) images only captures a finite amount of information from a scene; the goal of SR is to extract the independent information from each image in that set and combine the information into a single high resolution (HR) image (Pair Matching). The only requirement is that each LR image must contain some information that is unique to that image. This means that when these LR images are mapped onto a common reference plane their samples must be subpixel shifted from samples of other images – otherwise the images would contain only redundant information and SR reconstruction would not be possible. Most methods in SR are strictly reconstruction based; that is, they are based primarily on uniform and nonuniform sampling theorems and do not attempt to create any information not found in the LR images. There are also learning SR methods that create new information based on generative models.

SR techniques can prove useful in many different applications, and these applications can have different requirements in terms of both quality and computational complexity. The quality may also vary for different methods based on characteristics of the input image. The implementation complexity may be affected by implementation specifics, such as the availability of specific optimized libraries. Finally the artifacts caused by poor SR performance can be more visually distracting than blurring from interpolation. For these and other reasons choosing between SR methods is a complex task. A variety of approaches for solving the super-resolution problem have been proposed. Initial attempts worked in the frequency domain, typically recovering higher frequency components by taking advantage of the shifting and aliasing properties of the Fourier transform. Deterministic regularization approaches, which work in the spatial domain, enable easier inclusion of a priori constraints on the solution space (typically with smoothness prior). Stochastic methods have received the most attention lately as they generalize the deterministic regularization approaches and enable more natural inclusion of prior knowledge. Other approaches include non-uniform interpolation, projection onto convex sets, iterative back projection, and adaptive filtering. With the increased emphasis on stochastic techniques have also come increased emphasis on learning priors from example data rather than relying on more



# International Journal of Innovative Research in Computer and Communication Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 5, May 2016

heuristically derived information. To further improve the robustness of such an approach, we propose a more solid criterion for the adaptive regularization control in this work, based on the convergence property of the image energy change ratio between primitive and non-primitive fields during iterative regularization. By appropriately locating the turning point where regularization loses its efficacy in distinguishing primitive components from compression artifacts, the pair matching accuracy in learning-based SR can be steadily and greatly improved. In this way, the quantization noise is effectively eliminated while the missing high-frequency details are faithfully compensated. Moreover, the proposed single-image SR method can be directly applied into compressed video SR, by introducing certain interframe interactions on the regularization strength and simple spatial-temporal consistency optimization, as reported in our latest work [11]. Previous work on single-image SR can be roughly divided into four categories: interpolation-based [1]–[4], reconstruction-based [5], [6], classification-based [7] and learning-based [8]–[10].

## II. RELATED WORK

There are many different methods available for SuperResolution Image Reconstruction. We did comparison of some of the methods available. Algorithms are as follows:

### Nonuniform Interpolation

This approach is the most intuitive method for SR image reconstruction. In this approach three stages are performed successively.

1. Relative motion is estimated, i.e., registration if the motion information is not known.
2. Nonuniform interpolation is done to produce an improved resolution image, and
3. Process of deblurring is done depending on the observation model.

Non-uniform interpolation has relatively low computational complexity and it assumes that the blur and noise characteristics are identical across all LR images. The HR image on non-uniformly spaced sampling points is obtained with the relative motion information estimated. Then, the director iterative reconstruction procedure is followed to produce uniformly spaced sampling points. Once an HR image is obtained by non-uniform interpolation, we tackle the restoration problem to remove blurring and noise.

### 2.2 Frequency Domain

Aliasing which exists in all LR images is explicitly used to reconstruct HR image. Tsai and Huang [1] first derived a system equation that describes the relationship between LR images and a desired HR image by using the relative motion between LR images. The frequency domain approach is based on three principles:

1. The shifting properties of the Fourier transform.
2. The aliasing relationship between the continuous Fourier transform (CFT) of an original HR image and the discrete Fourier transform (DFT) of observed LR images.
3. The assumption that an original HR image is band limited.

These properties make it possible to formulate the system equation relating the aliased DFT coefficients of the observed LR images to a sample of the CFT of an unknown image. Main advantage of the frequency domain approach is theoretical simplicity, it means the relationship between LR images and the HR image is clearly demonstrated in the frequency domain. This method is also convenient for parallel implementation capable of reducing hardware complexity.

### 2.3 Nearest Neighbor algorithm

The Nearest Neighbor interpolation is the fastest and simplest option. It simply takes the color of a pixel and assigns it to the new pixels that are created from that pixel. Due to this simplistic approach, it does not create an anti-aliasing effect. This leads to problems with jaggies. Consequently, Nearest Neighbor interpolation is considered to be incapable of producing photographic quality work. It selects the value of the nearest pixel by rounding the coordinates of the

# International Journal of Innovative Research in Computer and Communication Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 5, May 2016

desired interpolation point  $x \geq 0$ . With an obvious extension to the two-dimensional case. Let  $\lfloor \cdot \rfloor$  is the floor operator: the largest integer less than or equal to the argument. As a result of this simplistic interpolation scheme, nearest neighbor doesn't have sub pixel accuracy and generates strong discontinuities, especially when arbitrary rotations and scale changes are involved. The only interesting property of this algorithm is the fact that it preserves the original noise distribution in the transformed image, which can be useful in some image analysis applications. This is most commonly used in-camera when reviewing and enlarging images to view details.

It simply makes the pixels bigger, and the color of a new pixel is the same as the nearest original pixel. **2.4 Bilinear Interpolation algorithm** Bilinear interpolation uses the information from a pixel (let's call it the original pixel) and four of the pixels that touch it to determine the color of the new pixels that are created from the original pixel.

Bilinear uses rather simple, linear calculations to do this. The Bilinear interpolation does have an antialiasing effect. However, it is not considered good enough for photo quality images. This takes the information from an original pixel, and four of the pixels that touch it, to decide on the color of a new pixel. It produces fairly smooth results, but it reduces the quality significantly. Images can become blurry.

## 2.5 Bicubic Interpolation algorithm

Bicubic interpolation uses the information from an original pixel and sixteen of the surrounding pixels to determine the color of the new pixels that are created from the original pixel. Bicubic interpolation is a big improvement over the nearest neighbor interpolation and bilinear interpolation methods for two reasons:

- (1) Bicubic interpolation uses data from a large number of pixels and
- (2) Bicubic interpolation uses a bicubic calculation that is more sophisticated than the calculations of the previous interpolation methods. Bicubic interpolation is capable of producing photo quality results and is probably the method most commonly used. This is the most sophisticated of the bunch, as it takes information from the original pixel and 16 surrounding pixels to create the color of a new pixel. Bicubic calculation is far more advanced than the other two methods, and it is capable of producing print quality images. Bicubic interpolation also offers the two variants of "Smoother" and "Sharper" for finely tuned results

### III. PROPOSED ALGORITHM

An overview of our single-image SR scheme in the compression scenario is shown in Fig. 1. Suppose  $X_0$  is an original HR image, it is first downsampled with a low-pass filter (mostly isotropic Gaussian) to form an LR measurement  $Y_0$ .

$$Y_0 = (g * X_0) \downarrow^\alpha \dots \dots \dots (1)$$

Where  $g$  is a decimation operator with scaling factor  $\alpha$ .  $Y_0$  is then compressed, resulting in a degraded LR measurement  $Y$

$$Y = Y_0 + E_Q \dots \dots \dots (2)$$

Where  $E_Q$  represents the quantization error introduced by compression in the spatial domain.

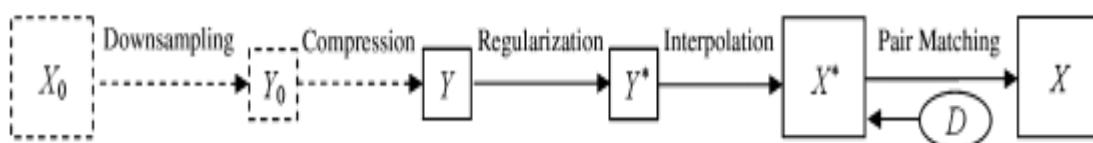


Fig. 1. Flowchart of our compressed image super-resolution scheme.



# International Journal of Innovative Research in Computer and Communication Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 5, May 2016

Y is the actual input of our SR system. This system consists of three modules: PDE regularization, bicubic interpolation and learning-based pair matching. Regularization is first performed on Y to get an artifacts-relieved LR image  $Y^*$

$$Y^* = f^N(Y) \dots \dots \dots (3)$$

Where  $f(*)$  denotes the PDE regularization functional and the superscript N represents the total iteration number of regularization, which determines the regularization strength.  $Y^*$  is then upsampled with scaling factor  $\beta$  to get an intermediate HR result  $X^*$

$$X^* = (h * Y^*) \uparrow^\beta \dots \dots \dots (4)$$

where h stands for the bicubic interpolation filter. The final HR image X is obtained after learning-based pair matching from  $X^*$  and a prepared database D.

## PDE Regularization

It consists in simplifying knowledge in a manner that only fascinating options are preserved. With this type of model, regularizing the image we will be similar to find a smooth surface. This may be done by directly designing PDE's (Partial Differential Equation) with specific regularization behaviours that evolve the noisy surface. Using regularization terms R in PDE's formulations like  $\partial I / \partial t = R$ , the data are iteratively regularized and a continuous sequence of smoother image I(t) is generated whereas the evolution time t goes by. A desired behaviour of such regularization algorithms is that the less significant data features disappear first, while the Interesting ones are preserved as long as they become unimportant themselves within the image. The isotropic regularization behaves like a low-pass filter suppressing high frequencies in the image. Unfortunately, image edges are high frequency signals as well as noise, so edges are eliminated. The need to find anisotropic regularization methods has then quickly appeared (in particular for image restoration purposes).

Therefore, isotropic diffusion smooths with equal strength in all directions and edges in the image will soon become blurred. Also, Heat equation is used for isotropic equation, given by

$$\Delta I = \left[ \frac{\partial I}{\partial t} = I \right]_{xx} + I_{yy} \tag{5}$$

For n iteration the edges are added to the initial image, using the following regularization

$$I_n = I_{n-1} + \lambda * \frac{\partial I}{\partial t} \tag{6}$$

Where,

- $I_n$  is the end resulting image after isotropic PDE smoothing.
- $I_{n-1}$  is the initial image
- $\frac{\partial I}{\partial t}$  or  $\Delta I$  is given by equation 1.
- $\lambda$  is the positive constant controlling the updating step.

Anisotropic PDE Regularization smooths the image and retains edges, i.e. smoothing is done along the edges not across it. Anisotropic smoothing can be viewed as joining of two 1D heat flows along the gradient direction and the isophote direction. Isophote are lines of equal light intensity. Note that  $\xi$  is everywhere tangent to the isophote lines  $I(x, y) = a$ , i.e. to the contours in the image. The set  $(\xi, \eta)$  is then a moving orthonormal basis whose configuration depends on the current point coordinates (x, y).

# International Journal of Innovative Research in Computer and Communication Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 5, May 2016

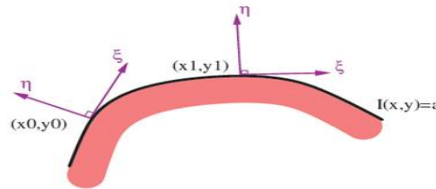


Fig.2 An image contour and its moving vector basis ( ξ, η)

The anisotropic Partial Differential Equation (PDE) is given by

$$\frac{dI}{dt} = C_{\xi} I_{\xi\xi} + C_{\eta} I_{\eta\eta} \quad (7)$$

Where,

$$I_{\xi\xi} = \frac{\partial^2 I}{\partial \xi^2} = \frac{i_x^2 - 2 * i_x * i_{xy} + i_y^2 * i_{xx}}{i_x^2 + i_y^2} \quad (8)$$

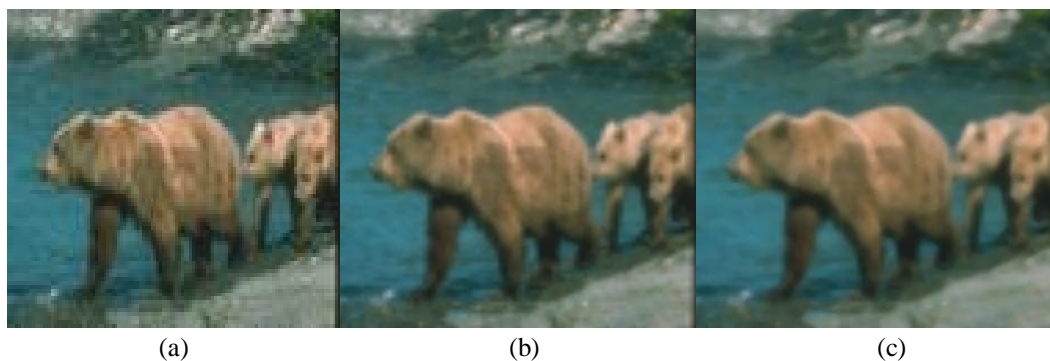
Where as  $\frac{\partial^2 I}{\partial \eta^2}$  can be obtained by taking the orthogonal of  $\frac{\partial^2 I}{\partial \xi^2}$ , as both are in orthogonal direction.  $\frac{\partial^2 I}{\partial \xi^2}$  computes the second order directional derivative of image I in the direction of  $\xi$ , which is opposite to gradient direction.  $\frac{\partial^2 I}{\partial \eta^2}$  Computes the second order directional derivative of image I in the direction of  $\xi$ , which is in the gradient direction.

## Pair Matching

The goal of the pair matching is to estimate the missing high-resolution details that aren't present in the interpolated image and which can't be visible by simple sharpening. To demonstrate the necessity and effectiveness of adaptive regularization in compressed image SR with learning-based methods, we then investigate the pair matching accuracy under three different circumstances, i.e., without compression, with compression but no regularization and with both compression and adaptive regularization.

## IV. RESULTS AND DISCUSSIONS

We test our SR scheme on both offline images degraded by designated down sampling and compression from the sources, as well as compressed thumbnail images on the web.



# International Journal of Innovative Research in Computer and Communication Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 5, May 2016

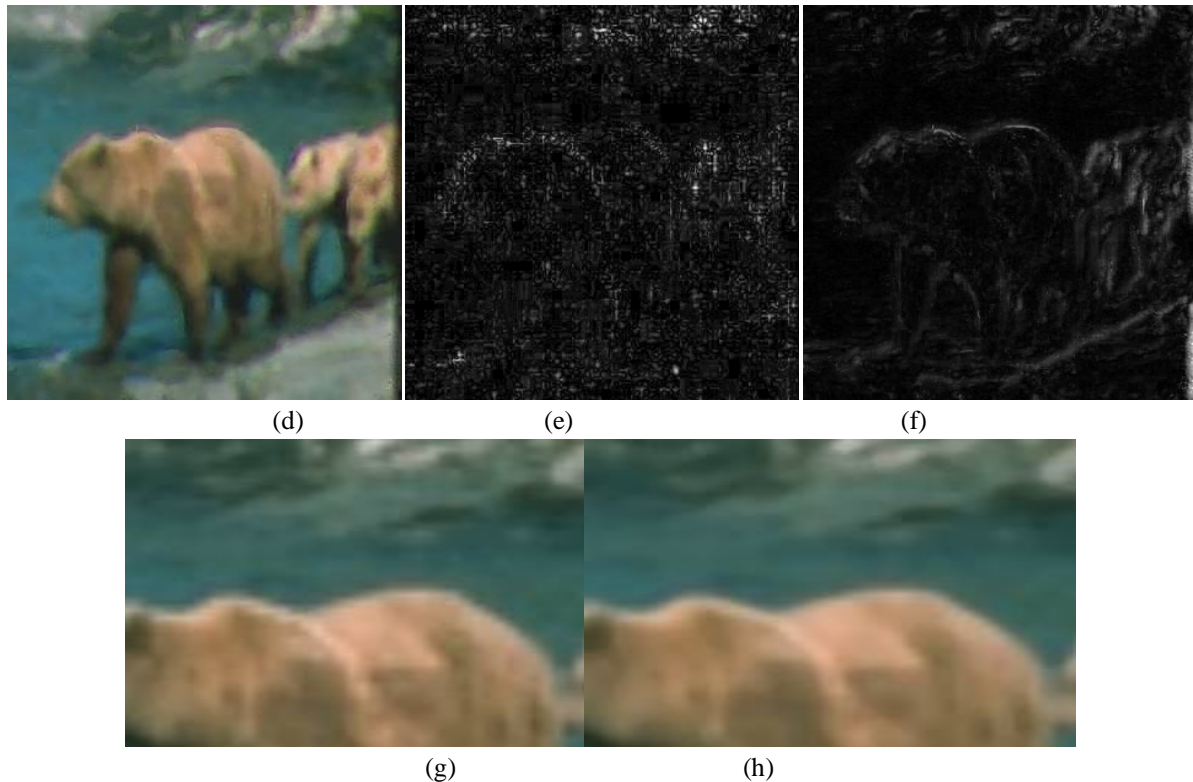


Fig.3 (a) Input image (b) Bicubic interpolation (factor of 2) (c) Anisotropic PDE regularization  
(d) Pair matching (e) Difference between (b) & (c) (f) Difference between (b) & (d)  
(g)Original image zoomed (h) Anisotropic smoothed version of zoomed image

## V. CONCLUSION

In this paper, we tend to present a robust single-image SR technique in the compression situation that is competent for at the same time increasing the resolution and perceptual quality of web image/video with completely different content and degradation levels. Our technique combines adjustable PDE regularization with learning-based pair matching to eliminate the compression artifacts and in the meantime best preserve and enhance the high-frequency details.

## REFERENCES

- [1] R. G. Keys, "Cubic convolution interpolation for digital image processing," *IEEE Trans. Acoust., Speech, Signal Process.*, vol. 29, no.12, pp. 1153–1160, Dec. 1981.
- [2] J. Allebach and P. W. Wong, "Edge-directed interpolation," in *Proc. IEEE Int. Conf. Image Processing*, 1996, vol. 3, pp. 707–710.
- [3] L. Xin and M. T. Orchard, "New edge-directed interpolation," *IEEE Trans. Image Processing*, vol. 10, no. 10, pp. 1521–1527, Oct. 2001.
- [4] Z. Xiong, X. Sun, and F. Wu, "Fast directional image interpolator with difference projection," in *Proc. IEEE Int. Conf. Multimedia & Expo*, 2009, pp. 81–84.
- [5] M. Irani and S. Peleg, "Motion analysis for image enhancement: Resolution, occlusion and transparency," *J. Vis. Commun. Image Represent*, vol. 4, pp. 324–335, Dec. 1993.
- [6] B. S. Morse and D. Schwartzwald, "Image magnification using level-set reconstruction," in *Proc. IEEE Conf. Computer Vision and Pattern Recognition*, 2001, pp. 333–340.
- [7] C. B. Atkins, C. A. Bouman, and J. P. Allebach, "Optimal image scaling using pixel classification," in *Proc. IEEE Int. Conf. Image Processing*, 2001, pp. 864–867.
- [8] S. Baker and T. Kanade, "Limits on super-resolution and how to break them," *IEEE Trans. Pattern Anal. Mach. Intell.*, vol. 2, no. 9, pp. 1167–1183, Sep. 2002.



ISSN(Online): 2320-9801  
ISSN(Print) : 2320-9798

# International Journal of Innovative Research in Computer and Communication Engineering

*(An ISO 3297: 2007 Certified Organization)*

**Vol. 4, Issue 5, May 2016**

- [9] C. Liu, H. Y. Shum, and C. S. Zhang, "A two-step approach to hallucinating faces: Global parametric model and local non-parametric model," in Proc. IEEE Conf. Computer Vision and Pattern Recognition, 2001, pp. 192–198.
- [10] W. T. Freeman and E. C. Pasztor, "Learning low-level vision," in Proc. IEEE Int. Conf. Computer Vision, 1999, pp. 1182–1189.
- [11] Z. Xiong, X. Sun, and F. Wu, "Web cartoon video hallucination," in Proc. IEEE Int. Conf. Image Processing, 2009, pp. 3941–3944.

## BIOGRAPHY



**K. Rajesh Kumar** completed his M.Tech in the stream of M.Tech (SSP). He is having teaching experience of more than 2 years in various Under Graduate and Post Graduate course. At present, he is working as Assistant Professor, Dept. of ECE, Keshav Memorial Institute of Technology, Hyderabad, Telangana, India.



**A.N. Sai Chakravarthy** completed his M.Tech in the stream of M.Tech (VLSI SD). He is having teaching experience of more than 2 years in various Under Graduate and Post Graduate course. At present, he is working as Assistant Professor, Dept. of ECE, Keshav Memorial Institute of Technology, Hyderabad, Telangana, India.