



International Journal of Innovative Research in Computer and Communication Engineering

(An ISO 3297: 2007 Certified Organization)

Vol. 4, Issue 5, May 2016

Energy Efficient A-Leach Routing Protocol

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ABSTRACT: Leach was the first most Routing Protocol used clustering concept in wireless sensor networks. Leach algorithm re-clustering process play vital role to gather data in cycles known as round. During each round a specific percentage of total nodes are elected as cluster heads (CHs). Each node get chance to become CH according to their probability in particular round. It is possible that not a single node is selected as CHs and few of nodes have to act as forced CH by ignoring residual energy, nodes location, and other significant parameter, which is the main reason for CH failure. Therefore to overcome this limitation Energy Efficient A-Leach Routing protocol is proposed which uses the forward/backward multi hop path approaches to increase the lifetime of WSNs and allow CHs to transmit their gathered data to Base Station (BS).

KEYWORDS: Leach, Ant-Leach(A-Leach), Base Station(BS), Cluster Head(CH), Ant Colony Optimization(ACO), Genetic Algorithm(GA), Gravitational Search Algorithm(GSA), Wireless Sensor Network(WSN).

I. INTRODUCTION

Wireless communication is based on the development of low-power, low-cost, multifunctional and very small nodes. These nodes are responsible for Sensing, data processing and communicating. The Sensor nodes are scattered in one area which sense the surrounding environment and collect the information from the surrounding environment and communicate through wireless links. The collection of Sensor nodes is known as wireless Sensor networks [1] [2]. The basic goals of Wireless Sensor Networks (WSNs) are:

- Gathering the information of surrounding environment like temperature of storage room.
- Count how many times temperature fall below 30 degree.
- Estimate parameters of the detected event.
- Classify detected object with other object.

Sensor nodes are those sensors which are responsible for gathering information by sensing and routing and then sending this information back to sink or BS. In WSNs nodes are connected to each other by direct or indirect links. Sensors provide information gathering ability from the physical world by converting physical phenomena to electrical signals. It is made up of two sub components: Sensors and simple to advance converters(ADCs). There are two types of sensors: Simple sensor and computerized sensor. Also there exist mix type of sensor that measure ecological parameters, such as temperature, light intensity, applied force, sound location, and type of object. The WSNs provide better understanding of the environment [3].

II. RELATED WORK

S. Aravindh. et.al (2012) proposed a combined hybrid algorithm approach is proposed in which ACO and GA (Genetic Algorithm) are used to find the shortest path. The paths generated by ant nodes are given input to GA. The GA finds the set of optimal possible routes by using selection, crossover and mutation process. The ACO concept is using to reduce the size of routing table. The worth of using GA is that it computes routes dynamically rather than making decision on the pre-computed route.



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U. Hari et.al (2013) proposed approach is to minimize the energy consumption of network by using multi-hop routing process with using Dijkstra's shortest path algorithm is used for data transmission. Proposed algorithm use unequal size cluster concept with parameters like distance between nodes and base station , degree of nodes and results shows it improve networks life time and performance matrix.

N.K. Sharad et.al (2013) proposed a comparison paper on ACO, GA and SA approach by solving travelling salesman problem. ACO gives better result in dynamic scenarios only for local optimization. With increases in number of iteration GA will provide better Energy Efficient Routing Protocol for Wireless Sensor Networks solutions and provide global solution. SA algorithm consume more computation time. This paper concludes that GA gives over all better result than ACO and SA.

S. Haidar. et.al (2014) proposed highly conserved to extend the WSNs lifetime. One method is to deploy the multiple sinks, which are more capable nodes in comparison to sensors. These increased the area coverage and reduce the communication distance between sensors and sinks.

III. ROUTING PROTOCOL FOR WSNs

Wireless sensor networks, is a self-establishing multi-hop wireless network, which works as a decentralized system and it does not pose fixed infrastructures. Conventional routing protocols do not compatible with at present WSN requirements: Sensors have low battery power, limited memory. The routing tables raise up with the network size and don't support diffusion communication. This is the main reasons to build more an energy efficient routing protocol for WSNs. [4] [5]

Characteristics of Routing Protocols

- It should be specific to the application.
- It should be data centric.
- It should be capable to perform data aggregation function.
- It must optimally use network resources such as bandwidth, computation power, and battery power etc.
- It should be capable of providing certain level of QoS as application demanded by network.
- End to end delay must be less.
- The number of packets collisions should be minimum.

III. CLASSIFICATION OF ROUTING PROTOCOLS

A WSNs might be classified in four ways, routing path establishment, network structure, protocol operation based, initiator of communication and application design of network [7][10]. As shown in table

Network Structure	Protocol Operation	
1. Flat Based	1. Negotiation Based	4. QoS Based
2. Hierarchical Based	2. Query Based	5. Coherent Based
3. Location Based	3. Multipath Based	

Table 1: Classification of Routing Protocol

Proactive protocol: It evaluates all the possible routes before they are essentially needed them and store these route information in a routing table. Routing tables store in nodes memory unit. When a route changes, its information has to be propagated throughout the network and time to time sensor nodes required to update their routing table. WSN consist of thousands of nodes, it's very difficult for nodes to maintain huge amount of routing information due to limited memory therefore proactive routing protocols are not well suit to WSN. Proactive protocols also called table driven routing protocols.

Reactive protocols: Protocols that falls under this type of category also called on demand routing protocols, because they only compute routes when it is required. This type of routing protocols do not exchange routes information periodically.

Hybrid routing protocol: It is the mixture of best feature of both proactive and reactive routing protocols.



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Location Based Protocol: This protocol finds the location of the sensor nodes depending upon the incoming signal strengths from source nodes. It generally tracks the location of nodes by using the location of neighbor nodes and others through GPS.

Hierarchical Protocols: The main design concern for any WSN is scalability. Thousands of sensor nodes are present in the network. Sensors are not enough capable to communicate over large distances. To overcome this issue, a hierarchical approach is used. Hierarchical routing works in two layers, the first one is used for clustering and the other layer is used for routing. The nodes having low energy are used for sensing activity and high energy nodes are used for processing and sending information to other nodes. It increases the network life time, energy efficiency, and delay etc.

Flat-based Protocols: No global identification number is assigned to nodes due to the less number of nodes present in the network field. Every node plays the same type of role. This protocol is also called data-centric routing, the sink node transmits query packets to certain regions and waits for a reply.

Coherent Protocols: The local data handling on the nodes can be differentiated between the coherent (minimum processing) and the non-coherent (full processing) routing protocols. The data is forwarded to the sink node after minimum processing like timestamping, duplicate suppression etc. when all source nodes send their data to the sink at the same time, a large amount of energy is consumed. To overcome this problem, a limited number of source nodes send data to the sink node.

Multipath based Protocols: It uses multiple paths rather than a single path for improving the WSN performance. For example, fault tolerance can be improved by maintaining multiple paths between the source and sink. It increases the cost of energy consumption and generates more traffic. The alternate paths are kept alive by sending periodic signals.

Negotiation-based routing: It is used for eliminating redundant data transmission. This consumes more energy, battery power, communication power, memory etc. To overcome this problem, a negotiation-based routing protocol is used, the sink or next node sends a negotiation message before transmission begins.

Query based protocols: The destination sensors propagate the query for data from a node through the network. A node having the same data sends back a reply message to the initiator's node. This sort of query uses natural language and high-level query language.

QoS-based protocols: When the process of data transmission is performed with the help of this routing, it balances the network's energy consumption and data quality through certain levels of QoS metrics such as delay time, energy used or the bandwidth.

IV. REVIEW OF LITERATURE

In WSNs, sensor nodes are organized into clusters. Each cluster is handled by a cluster head. The nodes of each cluster transmit their information with respect to their cluster head and these CHs transmit information to a base station or sink by using two-hop count distance. BS acts as a backbone connected to a wired network.

LEACH

In this paper, the main focus is on the hierarchical protocol LEACH. [6] [7]. Clustering is a type of energy-efficient communication protocol that can be used by the nodes to report sensed data to the sink. We have described layered protocols in which a network is composed of several clusters of sensors as shown in figure 4.1, different clusters are shown having different Cluster Head (CH) and Base station (BS). CH is responsible for organizing the data transmission events of all non-CH nodes in its cluster. Nodes are arranged into a cluster with a cluster head that is responsible for routing from the cluster to the other cluster heads or to base stations. Data travels from a lower clustered layer to a BS. While, it hops from one node to another node but as it hops from one layer to another and covers larger distances. It helps to move the data information faster to the base station. Clustering provides inherent optimization capabilities at the cluster heads [7].

LEACH Protocol is the first most protocol of hierarchical routing that has proposed data fusion, it has milestone significance in the clustering routing protocols. Many hierarchical routing protocols are improved based on LEACH protocol [9]. It is self-adaptive as well as self-organized. LEACH protocol uses its round as a unit, each round is made up of two stages (cluster set-up stage and steady stage), for the purpose of reducing unnecessary energy costs, the steady stage must be much longer than the set-up stage [20].

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The design goal performed by Leach are:

- The Randomized rotation of cluster heads nodes selection and the corresponding clusters.
- The Global communication reduction by the use of local compression.
- The Localized co-ordination and control for cluster configure and operation.
- Lower energy media access control.
- Application-specific data processing task

The Leach process is categorized into number of rounds and each of these rounds havemainly two different phases and these are known as:

Setup phase

- All the nodes are deployed randomly in the area
- Evaluated the nodes probability to become a cluster head by using

$$T(n) = \begin{cases} \frac{p}{1 - p(r \bmod \frac{1}{p})} & n \in G \\ 0 & \text{otherwise} \end{cases}$$

Where p is probability, r is number of round,G is set of nodes that have not beenCHs in the last 1/p rounds.

- The Advertisement of the cluster heads to its different individual cluster nodes.
- Transmission of the schedules plan that has been created during the setup phase.

Steady state

- The process of data aggregation within the separate clusters in the network.
- Compression of the sensed information that is sensed by the non-cluster headnode into its different cluster head within the cluster range.
- Transmission of the aggregated data to the base station through all electedcluster heads

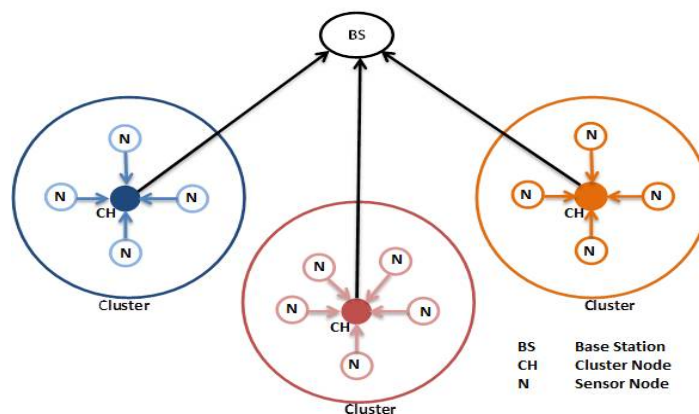


Fig. 1: Leach Protocol

Advantages of LEACH Protocol:

- Scalability of the WSNs is easy
- Single-hop Routing is possible from Sender node to cluster head for transmitting information.
- Role of CH can be distributed to other CH if required.
- Doesn't require the information of sensor node to create new cluster.
- Suitable for the application that needs constant monitoring of environment.

Disadvantages of LEACH Protocol:

- Relies on CH andCHs are not uniformly distributed.
- No inter-cluster communication is possible because CHs directly communicate with sink.



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- Require high range of transmission power in the network.
- Energy consumption is not considered.
- Doesn't work well with application that requires large area of coverage network.

Ant Colony Optimization [16]: ACO algorithm in which sensor nodes act like artificial ants, opt their basic features like forward and backward path construction, pheromone values evaporation rate to evaluate the fitness function of node by using three functions self-adaption, co-operation and competition. After number of iterations a single optimized path is constructed.

Genetic Algorithm

In GA nodes initialize as pollution by opting genetic behaviour, best fitness function result is considered as best pollution, to calculate fitness value three steps (crossover, mutation, selection) are repeated for particular number of generations to find local solution. It is best in case when we have two options for a solution.

Basic terminology used in Genetic Algorithm

- **Chromosome:** It is a set of genes that contains the solution in the form of genes. For e.g. 98150 is a chromosome value then 9,8,1,5 and 0 are its genes.
- **Population:** The total number of individuals or chromosome with same number of genes.
- **Fitness:** It is a value that assigned to an individual based on readiness of an individual to provide solution. Greater the fitness value, more appropriate solution will be obtained.
- **Fitness function:** It is an application oriented objective function which assigns fitness value to the individual.
- **Crossover:** Taking two fit individuals and then performs intermingling process to generate new two individuals.
- **Mutation:** It is a process of changing random genes in an individual value.
- **Selection:** The process of selecting individual to generate the new generation.

Gravitational Search Algorithm

GSA is a physical phenomenon based upon Law of Gravity and Law of Motion to find global optimized solution. Working of ACO and GSA is somewhat similar but computation functions are totally different. ACO selects one best solution among two different entities whereas GSA provides all over one best solution among population. The Gravitational Search Algorithm is considered as an isolated system for small artificial world of masses which obeying the Newton Law of gravitation and motion.

Law of gravity

It states that each particle attracts every other particle and the gravitational force between two particles is directly proportional to the product of their masses and inversely proportional to the distance between them [11]

$$F = G \left(\frac{M_1 M_2}{R^2} \right)$$

G is the gravitational constant, M1 and M2 mass of two particles and R is the distance between these two particles

Law of motion:

The current velocity of mass is equal to the sum of the fraction of its previous velocity and the variation in the velocity. Variation in the velocity or acceleration of any mass is equal to the force acted on the system divided by mass of inertia [11]. An acceleration is dependent on force and its mass.

$$a = \frac{F}{M}$$

F is force applied on an object, M is the mass, a is the acceleration

Fitness function computed from following equation

$$F_{ij}^d = G(t) \left(\frac{M_{pi}(t) * M_{aj}(t)}{R_{ij}(t) + \epsilon} \right) (x_j^d(t) - x_i^d(t))$$

$F_{ij}^d(t)$ is the force acting on agent i from agent j at d^{th} dimension and t^{th} iteration. $G(t)$ is the computed gravitational constant at the same iteration while ϵ is a small constant. $R_{ij}(t)$ is the Euclidian distance between two agents i and j at iteration t.

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Best fitness function computed as follow

Minimization Problems

$$best(t) = \min fit_j(t) \quad j \in (1 \dots \dots \dots N)$$

$$worst(t) = \max fit_j(t) \quad j \in (1 \dots \dots \dots N)$$

Maximization problems

$$best(t) = \max fit_j(t) \quad j \in (1 \dots \dots \dots N)$$

$$worst(t) = \min fit_j(t) \quad j \in (1 \dots \dots \dots N)$$

$fit_j(t)$ represents the fitness values of the j^{th} agent at iteration t, best(t) and worst(t) represents the best and worst fitness at iteration t.

Computation of Gravitational constant (G)

$$G(t) = G_0 e^{-\frac{\alpha}{T}}$$

G_0 and α are initialized at the starting, T is the total number of iterations.

Compute Masses of the agents

$$m_i(t) = \frac{fit_i(t) - worst(t)}{best(t) - worst(t)}$$

$$M_i(t) = \frac{m_i(t)}{\sum_j^N m_j(t)}$$

Compute Accelerations of agents

$$a_i^d(t) = \frac{F_i^d(t)}{M_{ij}(t)}$$

Acceleration of the i^{th} agents at iteration t

$$F_i^d(t) = \sum_{j \in kbest, j \neq i} rand F_{ij}^d(t)$$

F_i^d is the total force acting on i^{th} agents. Kbest is set of first K agents values with the best fitness value and biggest mass.

Energy consumption model

WSN use an energy attenuation model depending on the distance value between two nodes (Sender and Receiver). The transmitter transmits k bits data to another node, d is the meter distance between two nodes.

The energy consumption calculation formula

$$E_{TX}(k, d) = \begin{cases} kE_{ele} + kE_{fs}d^2 & d < d_0 \\ kE_{ele} + kE_{mp}d^4 & d \geq d_0 \end{cases}$$

$$E_{RX}(k) = kE_{ele}$$

$$E_{DA}(k) = kE_{da}$$

E_{mp} is multi path length energy value for transmission data, E_{fs} is for fixed path length energy value for transmission, E_{da} is the energy consumption used to compressed data unit. E_{TX} is transmission energy of sender, E_{RX} is received energy of the receiver, d_0 is the critical distance between two nodes.

V. RESEARCH METHODOLOGY

In previous works firstly cluster heads selected randomly then a probability parameter is used to select cluster heads. In proposed work cluster heads are selected with the help of GA process which gives us more appropriate value of node to become a cluster head. There is one issue in Leach protocol when no node gets a chance to become a cluster head [21].

GA approach also removes no cluster head formation issue. The major characteristics are:

- GA approach searches from a population of points rather than a single point.

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- GA use probabilistic transition rules rather than non-deterministic rules.
- GA use application oriented objective functions rather than not derivatives or other previous knowledge.
- GA sets parameter according to application rather than using predefined parameters.

We also try to bind limited range edge node with the GSA approach the major characteristics are following

- GSA proved us one best solution by evaluating overall force obtained by all particles rather than selecting best one from two particles.
- GSA consumes less memory as compare to others.
- Most of an optimization algorithms works on social behaviours while GSA inspired by a physical phenomenon of forces

Our proposed Methodology is divided in two parts setup phase and steady phase:

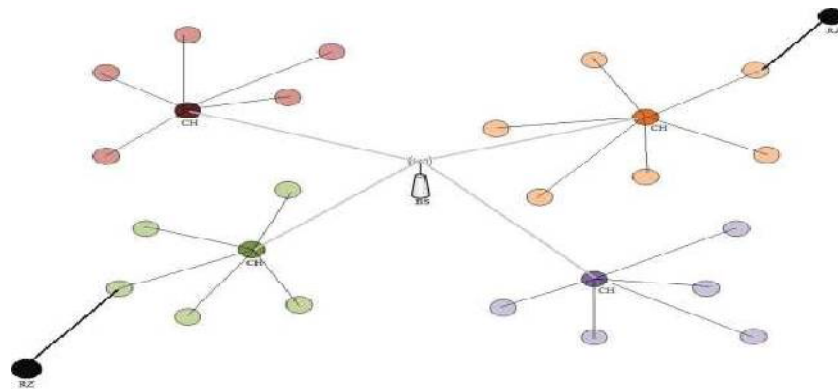


Fig.2: Proposed model of Wireless Sensor Networks

- BS is Base Station
- Four CH is selected Cluster Head in different clusters
- RZ either a node which is not in the range or not registered under any cluster

Setup phase

- Sensor nodes and base station are deployed in the sensor field.
- Invitational parameters are provided to sensor nodes so that they can start working.
- Cluster head is selected with the help of GA and sends the information about cluster to the base station. The information from base station is sent back to all nodes so that they can select their cluster heads.
- If any node is found out of range (RON) and not able to register itself under any cluster head then the gravitational search approach is used to find the path. When RON finds next hop it will automatically bind with cluster head by using the multi-hop concept.
- After step up phase completion we establish a cluster head link with base station and base station also have information about all node id's and their respective cluster heads.

Steady Phase

Time division multi access (TDMA) principle is used. In cluster a fixed time slot is provided to non-cluster head sensor nodes for transmission their data to the respective cluster heads. Due to non-uniform distribution of nodes some cluster heads either nearby or far away from the base station they use multi-hop path. Cluster head transmits their aggregate data to the base station. As a result, energy consumption by cluster heads gradually reduced and increased network life time

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VI. RESULTS AND DISCUSSIONS

The proposed routing protocol is simulated using MATLAB tool. Experiments are performed on simulations with different numbers of sensor nodes uniformly distributed in a 100 m×100 m. Base station is located at position [75,100].

Max_Round	No of Max Round	99999
ctrPacket_L	Length of packet that sent for nodes to CH	200 bits
Packet_L	Length of Packet that Sent for CH to BS	6400 bits
E_0	Initial energy of each node	0.5 nJ
E_{TX}	Energy for transferring of each bit (ETX)	50 nJ/bit
E_{RX}	Energy for receiving of each bit(ERX)	50 nJ/bit
E_{fs}	Energy of free space model	10e-12 J/bit
E_{mp}	Energy of multi path model	1.3e-15J/bit
E_{DA}	Data aggregation energy	5e-9 J/bit

Table 2: Simulation Parameters

Performance parameters

1. Network life time: The total number of nodes which are alive at end of all cycles of the algorithm. The below figure shows the number of rounds in which a node can become a CH in wireless network.

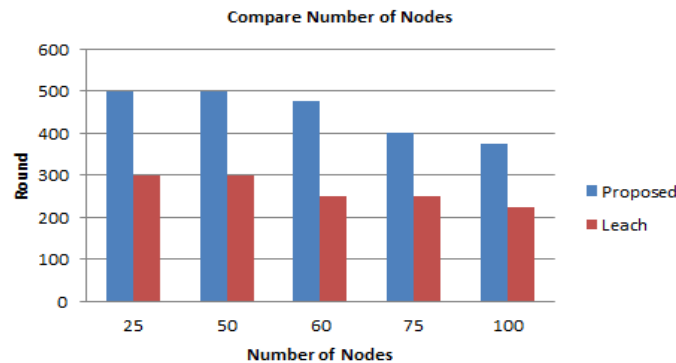


Fig. 3: Number of Rounds

2. Average Throughput: It is defined as the total number of packets delivered over the total simulation time (bits/sec.)

$$\text{Average Throughput} = \frac{N}{t \cdot r}$$

Where N is the total number of packets delivered to base station, t is the total time taken by data packet to transmit over network, r is the total number of cycles.

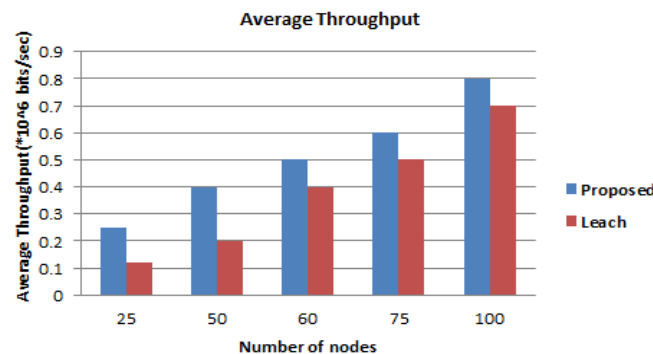


Fig. 4: Average Throughput Graph

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3. Energy efficiency: It is the total energy consumed in delivering 1000 bits of data to the base station (j/Kbits).

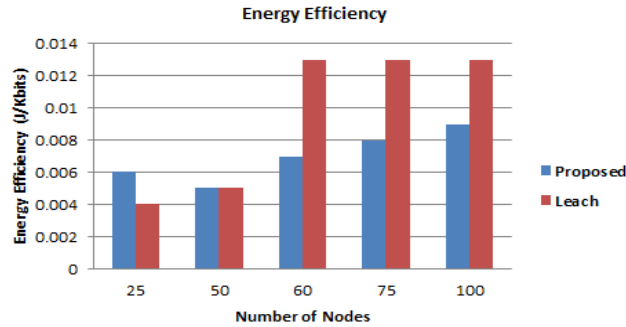


Fig. 5: Energy Efficiency Graph

5. Packet delivery ratio: It is defined as ratio of total packets received at base station to total packet generated by sender. We denoted it in %.

$$\text{Packet delivery ratio} = \frac{N}{n} * 100$$

Where N is the total number of packets delivered to base station, n is total number of packets transmitted by all nodes.

VII. CONCLUSION

Packet delivery ratio, delay time, average throughput of network, average energy consumption and network durability improvement is the main concern of the study. Along this we also try to find the best combination of technique which improves the performance parameters of network wireless network with the help of this research methodology. We are able to implement a hybrid routing protocol for wireless sensor network. Leach protocol limitations are overcome with this hybrid concept and result we get an energy efficient routing protocol which improves network life time, packet delivery ratio.

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