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Pursuance of Average Delay and Throughput Analysis on Ad Hoc Network Protocols

K. Vijayalakshmi¹, Dr. R. Manicka Chezian²

Research Scholar, Department of Computer Science, NGM College, Pollachi, India¹

Associate Professor, Department of Computer Science, NGM College, Pollachi, India²

ABSTRACT: A Mobile Ad-hoc Network (MANET) is a collection of wireless mobile nodes that communicates with each other without using any existing infrastructure or centralized supervision. There are several familiar routing protocols like AODV, DSR, DSDV.Network throughput and packet delay are the two most important parameters to evaluate the performance of wireless ad hoc networks. Generally it is difficult to achieve both high throughput and low packet delay by Dynamic Source Routing Protocol for Mobile Ad Hoc Networks (DSR) and Ad-Hoc On-demand Distance Vector (AODV) routing protocol. Based on the routing load (delay, throughput) and the connectivity, this paper systematically discusses the performance and comparison of three typical routing protocols of ad hoc networks with the different simulation model and metrics.

KEYWORDS: MANET, AODV, DSR, DSDV, Throughput and Delay

I. INTRODUCTION

An ad-hoc network is a collection of wireless mobile hosts forming a temporary network without the assistance of any centralized administration or any stand-alone infrastructure. If two wireless hosts are out of their transmission ranges in the ad hoc networks, other mobile hosts located between them can forward their messages, which effectively builds connected networks among the mobile hosts in the deployed area administration.[1] The former simulation modeled a network of 60 mobile hosts and varying pause times, the latter modelled sceneries with 50 nodes and pause time of 0, 30, 60, 120, 300, 600 and 900 s, respectively. Das et al. carried out the simulation analysis to AODV and DSR. Their simulation has a model of 50 (the first group of experiment) and 100 (the second group of experiment) nodes at varying pause times or mobility speeds. This paper considers the simulation model with a dynamic network size and a nivariable pause time which should be zero under weakest case. So we investigate performances of the routing protocols from different categories under various network scenarios (e.g., different network size, mobility speeds, etc.). This paper systematically discuses the performance evaluation and comparison of three typical routing protocols, AODV, DSDV, DSR and in ad hoc networks, which take the QoS (delay, throughput), routing load and connectivity as evaluation metrics.

II. RELATED WORK

Layman et al. have discussed throughput with other metric like average delay analysis, jitter analysis, loss ratio analysis, routing load analysis. Routing algorithm. The node mobility speed is varying between 0 and 40 m/s and the pause time is 0 s. Each simulation executes for 300 s. It is concluded that Temporally- Ordered Routing Algorithm has a lowest routing load and a good scalability. Ad-hoc On-demand Distance Vector displays the smallest delay and loss ratio and the greatest throughput [1] Different author's analysis and ideas on Throughput and Delay is given in the following table 1.



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Table 1: Analysis of Throughput and Delay

AUTHORS	ANALYSIS OF THROUGHT AND DELAY
Gupta ,kumar et al.,	Introduced random network [4]model for studying throughput scaling in a fixed wireless network
M.Grossglauser et al.,	Showed that at the time of movement nodes,[5]the throughput scaling changes completely.
A. El-Gamal et al,.	Showed that the throughput and the delay are characterized by three parameters the number of hops, the transmission range, and The authors propose schemes that exploit the three features to obtain different points on the through- put-delay curve in an optimal way.
L.Ying et al,.	The tradeoffs delay-throughput is the object of a study for the authors of the paper. The same authors developed an algorithm to achieve the optimal tradeoffs delay-throughput on certain conditions on the delay.

III. ROUTING PROTOCOLS IN MANET

Ad-hoc routing protocol setup the path, exchange information and take decision of runtime path. In this paper we work on reactive routing(AODV,DSR) and Hybrid Routing (ADV) Proactive Routing Proactive routing protocols are based on shortest path algorithms. It maintains and update information on routing among all nodes of a given network at all times even if the paths are not currently being used. [5]Thus, even if some paths are never used but updates regarding such paths are constantly broadcasted among nodes. Route updates are periodically performed regardless of network load, bandwidth constraints In this paper we work on reactive routing(AODV,DSR) and Hybrid Routing (ADV) There is three types of topology based routing

- 1. Proactive (table-driven) routing protocols
- 2. Reactive (on-demand) routing protocols
- 3. Hybrid routing protocols

Reactive Routing On demand or reactive routing protocols were designed to overcome the overhead problem, that was created by proactive routing protocols, by maintaining only those routes that are currently active. These protocols implement route determination on a demand or need basis and maintain only the routes that are currently in use, thereby reducing the burden on the network when only a subset of available routes is in use at any timeAODV maintains and uses an efficient method of routing that reduces network load by broadcasting route [3,6]discovery mechanism and by dynamically updating routing information at each intermediate node. Route discovery in AODV can be done by sending RREQ (Route Request) from a node when it requires a route to send the data to a particular destination.

A.DYNAMIC SOURCE ROUTING PROTOCOL (DSR)

The Dynamic Source Routing (DSR) protocol is an on- demand reactive unicast routing protocol based on source routing. DSR protocol is composed by two "on-demand" mechanisms, which are requested only when two nodes want to communicate with each other. In DSR, each node uses buffer technology to keep route information of all the nodes. There are two major phases in DSR such as:

- 1. Route discovery
- 2. Route maintenance

In DSR, every mobile node in the network needs to maintain a route cache where it caches source routes that it has learned. When a host wants to send a packet to some other host, it first checks its route cache for a source route to the destination. In the case a route is found, the sender uses this route to propagate the packet. [8,9]Otherwise the source node initiates the route discovery process. Route discovery and route maintenance are the two major parts of the DSR protocol.

B..AODV

The Ad-Hoc On-demand Distance Vector (AODV) routing protocol [7, 11] is one of several published routing protocols for mobile ad-hoc networking. Wireless ad-hoc routing protocols such as AODV are currently an area of much research among the networking community. Thus, tools for simulating these protocols are very important. Since



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one of the goals is scalability, I have strived to make the code as efficient as possible. For example, I implemented an expanding ring search algorithm to limit the flood of RREQ messages Throughout the development process, I have used simulation programs which I have written to test and harden the code. Each AODV router is essentially a state machine that processes incoming requests from the SWANS network entity. [11]

Each routing table entry consists of the following fields:

- 1. Destination address
- 2. Next hop address
- 3. Destination sequence number

If a route exists, the router simply forwards the message to the next hop.Otherwise, it saves the message in a message queue, and then it initiates a route request to determine a route.





AODV nodes use four types of messages to communicate among each other. Route Request (RREQ) and Route Reply (RREP) messages are used for route discovery. Route Error (RERR) messages and HELLO messages are used for route maintenance. [12] The following sections describe route determination and route maintenance in greater detail.

Parameters	AODV	DSR
Source routing	No	Yes
Topology	Full	Full
Broad cast	Full	Full
Update	Route Error	Route Error
Information		
Update	Source	Source
Destination		
Method	Unicast	Unicast
Storage	O(E)	O(E)
Capacity		

Table2: Comparison between AODV, DSR

C.DESTINATION-SEQUENCED DISTANCE-VECTOR (DSDV)

The Table-driven DSDV protocol is a modified version of the Distributed Bellman-Ford (DBF) Algorithm that was used successfully in many dynamic packet switched networks [14]. The Bellman-Ford method provided a means of calculating the shortest paths from source to destination nodes, if the metrics (distance-vectors) to each link are known. DSDV uses this idea, but overcomes DBF's tendency to create routing loops by including a parameter called destination-sequence number. On reception of these update messages, the neighbouring nodes use the following algorithm to decide whether to ignore the update or to make the necessary changes to its routing table

Step 1: Receive the update message

Step 2: Update the routing table if any one of the following condition satisfies:

i) Sn > Sp

ii) Sn=Sp , Hop count is less

Otherwise, ignore the update message. Here, Sn and Spare the Sequence numbers of new message and existing message respectively. When a path becomes invalid, due to movement of nodes, the node that detected the broken link



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is required to inform the source, which simply erases the old path and searches for a new one for sending data. The advantages are latency for route discovery is low and loop-free path is guaranteed. The disadvantage is the huge volume of control messages.

IV. THROUGHPUT AND DELAY

Throughput: Suppose packets arrive at node j as a Bernoulli process of rate j packets/slot, i.e., a packet arrives during the current slot with probability j, and otherwise no packet arrives. Other stochastic arrival flows with the same average rate can be treated similarly, and the arrival model does not affect the region of rates the network can support.[13]Thus, the per-node capacity of the network is the maximum rate that the network can stably support. Throughput is the average number of successfully delivered data packets on a communication network or network node. In other words throughput describes as the total number of received packets at the destination out of total transmitted packets. Throughput is calculated in bytes/sec or data packets per second. Mathematically,throughput is shown as Equation 1

Throughput (bytes/sec) = Total number of received packets at destination* packet size

----- kb/s Total simulation time

eq(1)

Delay: The delay of a packet is the time it takes from the source to reach its destination. The total network delay is the expectation of the average delay over all packets, all S-D pairs, and all random network configurations in the long term. The average End-to-End Delay AVG T is calculated as showing in Equation 2

 $\begin{array}{l} T_{AVG} = \sum_{Nt} \sum_{i=1}^{Ni} (Ht^{i} - Hi_{t}) \\ Nt = the total number of packets received \end{array}$

eq(2)

V. AVERAGE DELAY AND THROUGHPUT ANALYSIS

Ht= emission instant of package

DSDV exhibits a shorter delay because it is a kind of table-driven routing protocol; each node maintains a routing table in which all of the possible destinations with the network and the number of hops to each destination are recorded, only packets belonging to valid routes at the ending instant get through. A lot of packets are lost until new (valid) route table entries have been propagated through the network by the route update messages in DSDV. The literature [15] has drawn a conclusion that DSR has a lower delay than AODV with a longer pause time. In our simulation experiments environment of high-speed movement and an increasing network size, DSR has always a longer delay than AODV. This is mainly in that the different simulation models are applied in table 3.

AODV	DSDV	DSR
1.2	0.8	3.8
0.8	0.1	2.8
0.1	0.4	0.9
0.1	0.4	3.2
1.7	1.7	4.3

Table 3: Average Delay in Different Protocols



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FIG 2: Average Delay versus Number of Nodes

A. AVERAGE THROUGHPUT ANALYSIS

The average end to end throughput for the network is shown in Figs. 2 and 3, which reflects the usage degree of the network resources for the typical routing protocols. For the convenience to comparison, Fig. 2 only demonstrates the throughput-changing curve with the number smaller than 50, and Fig. 3 presents the complete simulation"s throughput changing curve. With an offered load of 1 packets/s the maximum throughput is approximately 4500 kbps. Throughput increases quickly for AODV, DSR and DSDV with increased number of nodes. TORA on the other hand has difficulties in finding routes when number increases, [16]which is clear from Fig. 3, where the throughput drops slightly with the number smaller than 50. [16]AODV is still the highest with the number exceeding 50, but this time DSDV has a better throughput. Throughput is the total of all bits (or packets) successfully delivered to individual destinations over total-time / total- time (or over bits-total / total time) and result is found as per KB/Sec. In AODV, the throughput increases with respect to number of nodes increases except network size 100, but very slowly because delay is very high. In DSDV, the throughput increases with respect to number of nodes increases except network size 100, similar to AODV. Sometimes in data packets per second or data packets per time slot. From graph we can analyze as number of node increase in network throughput gets better.



FIG 3: Average Throughput versus Number of Nodes

B.PARAMETER VALUES BY VARYING SPEED OF THE MOBILE NODES

The number of nodes was varied (5ms,10ms,20ms) each time in and the throughput was calculated at destination node during entire AODV shows higher throughput than the DSR and DSDV. Finally, by varying the number of nodes (30,40 and 50) and also by varying the speed(5ms,10ms,20ms) of the nodes then calculate the parameter values such as throughput, control overhead, average end to end delay and packet delivery ratio. The AODV has much more routing packets than DSR because this avoids loop and freshness of routes while DSR uses stale routes. Among these



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three routing protocols AODV is better than other two routing protocols and DSR have slightly lower throughput than AODV. The following table represent parameter values in different routing protocol shown in table 4.

Table 4: PARAMETER VALUES BY VARYING SPEED OF THE MOBILE NODES

Parameter	5 ms			10 ms			20 ms		
measured	AODV	DSR	DSDV	AODV	DSR	DSDV	AODV	DSR	DSDV
No of packets	579	567	558	570	554	561	557	561	559
send									
No of packets	576	568	494	566	553	344	550	556	367
received									
Delay	0.01163	0.01003	0.00885	0.01432	0.0142	0.00988	0.01969	0.01103	0.00658
Throughput	25170.1	23903.7	21607	24728	23247	15172	24067	23376	10638







As it can be seen from the above simulation, end to end delay is higher in AODV followed by DSR and DSDV having the lowest and most stable End to End Delay in mobility. By increasing number of nodes in small area then reduce the end to end delay in AODV and increasing speed of the node then increase the delay in AODV. In DSR and DSDV slightly lower delay compared to AODV.

VI. CONCLUSION

Each mobile node in a MANET acts as a router by forwarding the packets in the network. Hence, one of the challenges in the design of routing protocols is that it must be tailored to suit the dynamic nature of the nodes. Throughput and Delay performance is discussed from various authors. From the analysis AODV performance is the best considering its ability to maintain connection by periodic exchange of data's. As far as Throughput and Delay is concerned, AODV and DSR perform better than DSDV even when the network has large number of nodes. The related work uses the simulation model with a constant network size and varying pause time. It is concluded that in End-to-End delay and throughput of DSR and AODV showed better results than DSDV. In Future we discuss the impacts of location popularity on scaling laws of MANETs. To analyze the Delay and Throughput, and find the performance is worse than that of uniform scenarios.

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BIOGRAPHY



K.Vijayalakshmi is a Research Scholar in Department of Computer Science, Nallamuthu Gounder Mahalingam College, and Pollchi. She received her Master of Computer Science (M.Sc) in 2014 from Nallamuthu Gounder Mahalingam College, Pollachi under Bharathiar University, Coimbatore. She has presented papers in National conferences and attended Workshop, Seminars. Her research focuses on advanced networking.



Dr. R. Manicka chezian received his M.Sc Applied Science from PSG College of Technology, Coimbatore, India in 1987. He completed his M.S. degree in Software Systems from Birla Institute of Technology and Science, Pilani, Rajasthan, India and Ph.D degree in Computer Science from School of Computer Science and Engineering, Bharathiar University, Coimbatore. He has 25 years of Teaching experience and 17 years of Research Experience. He served as a Faculty of Maths and Computer Applications at P.S.G College of Technology, Coimbatore from 1987 to 1989. Presently, he is working as an Associate Professor of Computer Science in NGM College (Autonomous), Pollachi, India. He has published more then 120 papers in various International Journals and

Conferences. He is a recipient of many awards like Desha Mithra Award and Best paper Award. He is a member of various Professional Bodies like Computer Society of India and Indian Science Congress Association. His research focuses on Network Databases, Data Mining, Data Compression, Mobile Computing and Real Time Systems, Network Security, Bio-Informatics.